EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	487874	(detect\$3 or sens\$3 or monitor\$3 or track\$3) near7 (individual or driver or passenger or child or person or human or object)	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 14:46
L2	131545	1 and (camera or CCD or video or ("3" near2 (D or dimension\$\$4)) or depth)	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 14:48
L3	1090265	(part\$4 or sub or portion) near2 (model or body or frame or figure or face or person or individual or driver or passenger or eye or child)	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 14:52
L4	13	3 near7 (select\$3 or choos\$3 or retriev\$3) near5 hierarchic\$5	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 15:12
L5	3	1 and 2 and 4	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 14:58
L6	515	3 near4 (position or location) near7 ((different or other or next) near3 (body or part or portion or structure or facial or head or ear or nose or eye))	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 15:01
L7	0	5 and 6	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 15:01
L8	51	2 and 6	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 15:15
L9	0	8 and ((select\$3 or choos\$3 or retriev\$3) near5 hierarchic\$5)	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 15:16
L10	2	("6717518").PN.	USPAT; EPO; JPO; DERWENT	OR	OFF	2007/03/22 15:15
L11	1	2 and 3 and 10	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 15:15
L12	0	11 and ((select\$3 or choos\$3 or retriev\$3) near5 hierarchic\$5)	USPAT; EPO; JPO; DERWENT	OR	ON	2007/03/22 15:16

US 6714201 B1 US 6535435 B2 US 6335893 B1 Apparatuses, method: 345/474 700/61 Reference voltage ger 365/189.0! 365/175; 365/179 Semiconductor integr: 365/226 257/E27.097; 365/189.09

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iviethod and apparatus6

US 5052406 A US 4973156 A US 4947850 A US 4935093 A US 4894908 A US 4867554 A US 4815190 A	Method and apparatus 600/431 Method for the continu 216/6 Method for automated 29/711 Surface examining ap 351/205 Method for automated 29/430	600/476 216/20; 216/41; 257/E27.114; 29, 29/783; 29/784 351/206; 351/221 198/346.1; 198/465.1; 29/701; 29		
WO 2003107259 A	Person locating method, in which	a depth sensor is used to general		
LS				

